

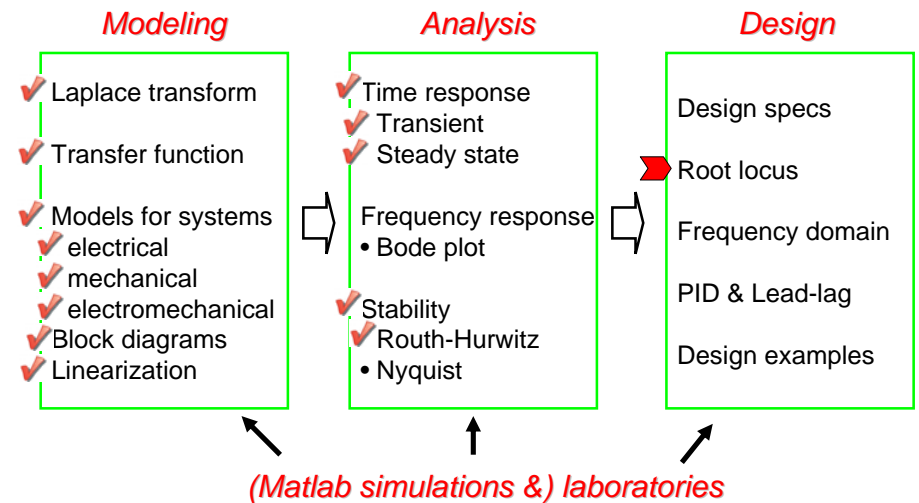
ME451: Control Systems

Lecture 16 Root locus

Dr. Jongeun Choi
Department of Mechanical Engineering
Michigan State University

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Course roadmap



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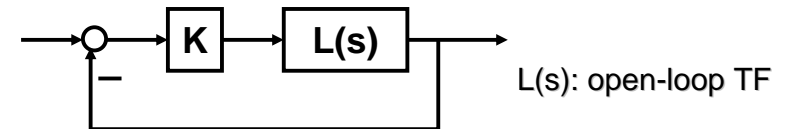
Lecture plan

- L16: Root locus, sketching algorithm
- L17: Root locus, examples
- L18: Root locus, proofs
- L19: Root locus, control examples
- L20: Root locus, influence of zero and pole
- L21: Root locus, lead lag controller design

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What is Root Locus?

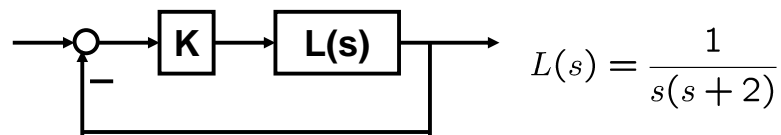
- W. R. Evans developed in 1948.
- **Pole location** of the feedback system characterizes **stability** and **transient properties**.
- Consider a feedback system that has one parameter (gain) $K > 0$ to be designed.



- **Root locus** graphically shows how poles of CL system varies as K varies from 0 to infinity.

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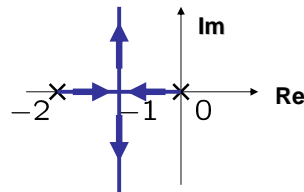
A simple example



- Characteristic eq. $1 + K \frac{1}{s(s+2)} = 0$ Closed-loop poles

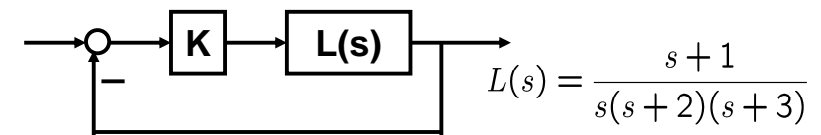
→ $s^2 + 2s + K = 0$ → $s = -1 \pm \sqrt{1 - K}$

- K=0: s=0,-2
- K=1: s=-1,-1
- K>1: complex numbers



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A more complicated example



- Characteristic eq. $1 + K \frac{s+1}{s(s+2)(s+3)} = 0$

→ $s(s+2)(s+3) + K(s+1) = 0$ → $s = ???$

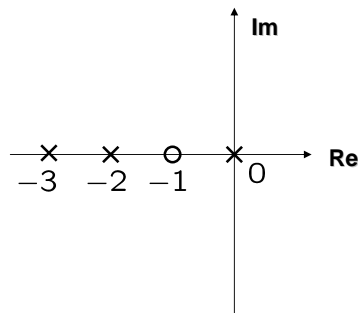
- It is hard to solve this analytically for each K.
- Is there some way to **sketch roughly** root locus by hand? (In Matlab, use command "rlocus.m".)

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Root locus: Step 0

- Root locus is symmetric w.r.t. the real axis.
- The number of branches = order of L(s)
- Mark poles of L with "x" and zeros of L with "o".

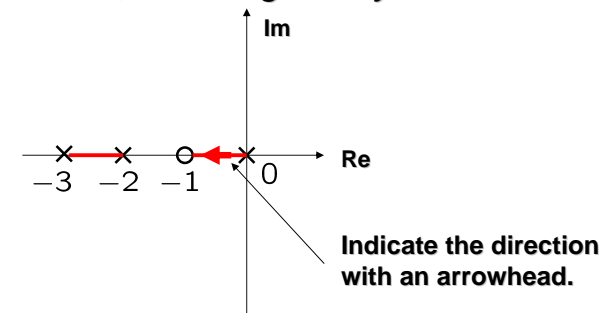
$$L(s) = \frac{s+1}{s(s+2)(s+3)}$$



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Root locus: Step 1

- RL includes all points on real axis to the left of an odd number of real poles/zeros.
- RL originates from the poles of L and terminates at the zeros of L, including infinity zeros.



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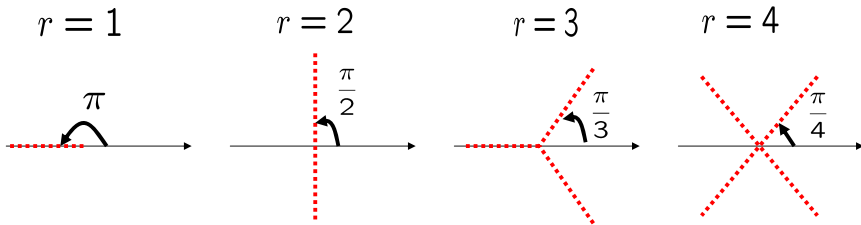
Root locus: Step 2 (Asymptotes)

- Number of asymptotes = relative degree (r) of L :

$$r := \underbrace{n}_{\text{deg}(\text{den})} - \underbrace{m}_{\text{deg}(\text{num})}$$

- Angles of asymptotes are

$$\frac{\pi}{r} \times (2k + 1), \quad k = 0, 1, \dots$$

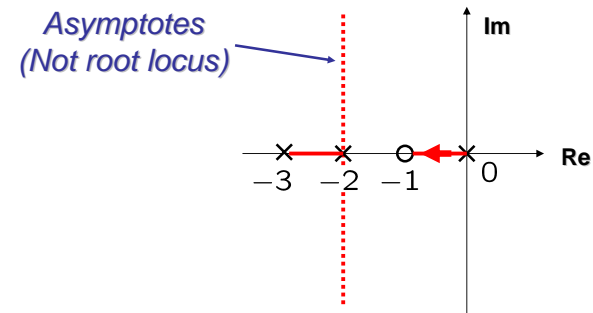


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Root locus: Step 2 (Asymptotes)

- Intersections of asymptotes $\frac{\sum \text{pole} - \sum \text{zero}}{r}$

$$L(s) = \frac{s+1}{s(s+2)(s+3)} \rightarrow \frac{\sum \text{pole} - \sum \text{zero}}{r} = \frac{(0 + (-2) + (-3)) - (-1)}{2} = -2$$



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Root locus: Step 3

- Breakaway points are among roots of $\frac{dL(s)}{ds} = 0$

Points where two or more branches meet and break away.

$$L(s) = \frac{s+1}{s(s+2)(s+3)} \rightarrow \frac{dL(s)}{ds} = -2 \frac{s^3 + 4s^2 + 5s + 3}{(s(s+2)(s+3))^2} = 0 \quad (*)$$

$$\rightarrow s = -2.4656, -0.7672 \pm 0.7926i$$

For each candidate s , check the positivity of $K = -\frac{1}{L(s)}$

$$\rightarrow K = 0.4186, 1.7907 \mp 4.2772i$$

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Quotient rule

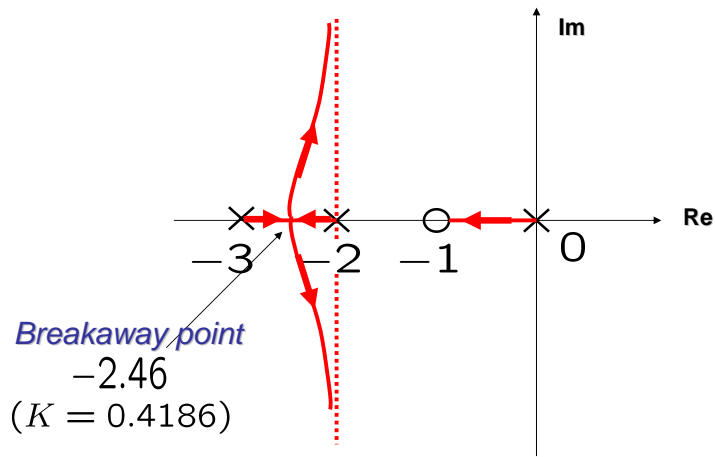
$$\left(\frac{N}{D}\right)' = \frac{N'D - ND'}{D^2}$$

$$\left(\frac{s+1}{s(s+2)(s+3)}\right)' = \frac{s(s^2 + 5s + 6) - (s+1)(3s^2 + 10s + 6)}{(s(s+2)(s+3))^2}$$

$$= \frac{-2s^3 - 8s^2 - 10s - 6}{(s(s+2)(s+3))^2}$$

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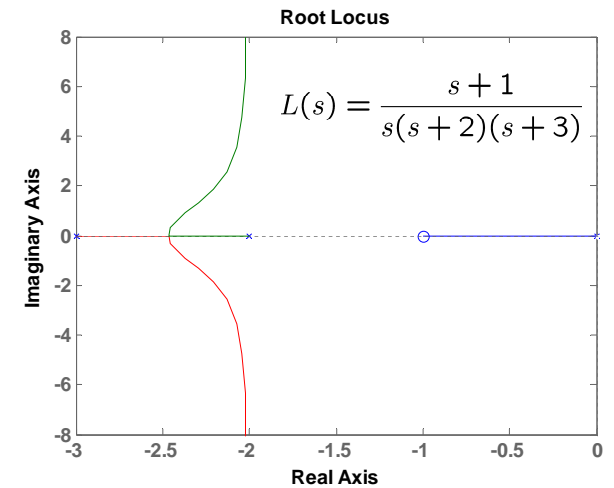
Root locus: Step 3



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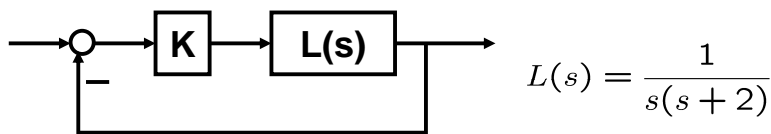
Matlab command "rlocus.m"

```
num=[1 1];
den=[1 5 6 0];
sys=tf(num,den);
rlocus(sys)
```



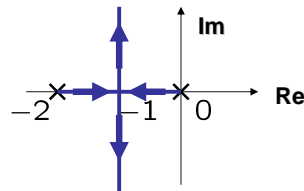
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A simple example: revisited



Asymptotes

- Relative degree 2
- Intersection $\frac{0 + (-2)}{2} = -1$



Breakaway point

$$L'(s) = \frac{-(2s+2)}{s^2(s+2)^2} = 0 \rightarrow s = -1$$

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Summary and exercises

- Root locus
 - What is root locus
 - How to roughly sketch root locus
- Sketching root locus relies heavily on experience. **PRACTICE!**
- To accurately draw root locus, use Matlab.
- Next, more examples
- Exercises
 - Read Chapter 7.

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Exercises

$$L(s) = \frac{1}{s}$$

$$L(s) = \frac{1}{s^2}$$

$$L(s) = \frac{1}{s^3}$$

$$L(s) = \frac{1}{s(s+4)}$$

$$L(s) = \frac{s+1}{s(s+2)}$$

$$L(s) = \frac{1}{s(s+1)(s+5)}$$